

Polynomial Systems Theories in Biology

Talk at ACA 2022

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<https://matthewengland.coventry.domains/dewcad/index.html>
EPSRC Grants EP/T015748/1 and EP/T015713/1

¹Partially supported by EU H2020 project SC² (712689), and wholly supported by DEWCAD colleagues

- 1 Background
- 2 Parametric Occurrence of Multiple Steady States
[BDE⁺17, EEG⁺17, BDE⁺19]
- 3 Expected number of positive real solutions in reaction networks [FS20]
- 4 Personal Conclusions

Prehistory at Bath

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We could show that there was scope for applying computer algebra to enzyme kinetic reactions.

Polynomial Systems Theories

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All are doubly-exponential worst case in the number of variables (including parameters): [BD07, DH88, MM82, MR13].

Parametric Occurrence of Multiple Steady States

[BDE⁺17, EEG⁺17, BDE⁺19]

- We aim to identify symbolically regions of a parameter space over which a biological network exhibits **multi-stationarity** (multiple steady states).

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- Specifically, we consider the **Mitogen-Activated Protein Kinases (MAPK)** cascade. We have results for models # 26 (and # 28) in the Biomodels Database².
- In contrast to most of the literature on the topic, we work with methods from **Symbolic Computation** (where values are exact rather than floating point).

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MAPK – what and why?

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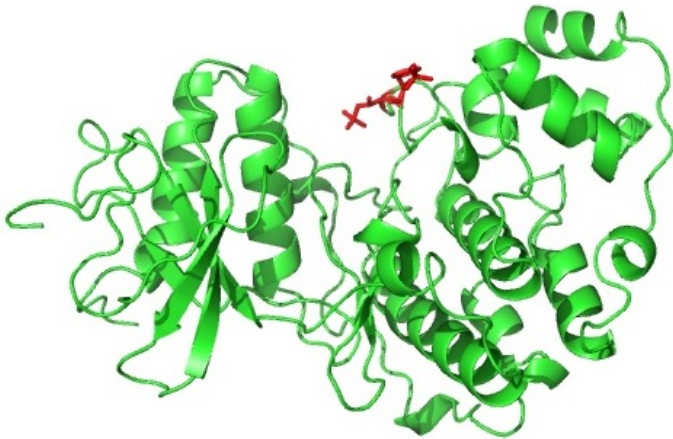
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Why study multistationarity?

- Instrumental to cellular memory and cell differentiation during development or regeneration of multicellular organisms.
- Used by micro organisms in survival strategies.

MAP: Phosphorylated residues are displayed in red

X-ray structure of the ERK2 MAP kinase in its active form



Source: Wikipedia - via molecular visualization system PyMol.

This is work of an interdisciplinary group including researchers from Mathematics, Computer Science, and Systems Biology. Naturally, our focus here will be on symbolic computation aspects.

Why use symbolic methods for this problem?

- Numerical methods observed to give incorrect results at certain points in parameter space.
- Symbolic methods have the scope to give semi-algebraic descriptions of parameter space: the exact solution.

Case Study: Model 26

From: www.ebi.ac.uk/biomodels-main/BIOMD0000000026

$$\dot{x}_1 = k_2x_6 + k_{15}x_{11} - k_1x_1x_4 - k_{16}x_1x_5$$

$$\dot{x}_2 = k_3x_6 + k_5x_7 + k_{10}x_9 + k_{13}x_{10} - x_2x_5(k_{11} + k_{12}) - k_4x_2x_4$$

$$\dot{x}_3 = k_6x_7 + k_8x_8 - k_7x_3x_5$$

$$\dot{x}_4 = x_6(k_2 + k_3) + x_7(k_5 + k_6) - k_1x_1x_4 - k_4x_2x_4$$

$$\dot{x}_5 = k_8x_8 + k_{10}x_9 + k_{13}x_{10} + k_{15}x_{11} - x_2x_5(k_{11} + k_{12}) - k_7x_3x_5 - k_{16}x_1x_5$$

$$\dot{x}_6 = k_1x_1x_4 - x_6(k_2 + k_3)$$

$$\dot{x}_7 = k_4x_2x_4 - x_7(k_5 + k_6) \quad 11 \text{ differential equations}$$

$$\dot{x}_8 = k_7x_3x_5 - x_8(k_8 + k_9) \quad 11 \text{ variables}$$

$$\dot{x}_9 = k_9x_8 - k_{10}x_9 + k_{11}x_2x_5 \quad 16 \text{ parameters}$$

$$\dot{x}_{10} = k_{12}x_2x_5 - x_{10}(k_{13} + k_{14})$$

$$\dot{x}_{11} = k_{14}x_{10} - k_{15}x_{11} + k_{16}x_1x_5$$

The biomodels database also gives us meaningful values for the rate constants.

- Some are measured:

$$\begin{array}{lll} k_1 = 0.02, & k_3 = 0.01, & k_4 = 0.032, \\ k_7 = 0.045, & k_9 = 0.092, & k_{11} = 0.01, \\ k_{12} = 0.01, & k_{15} = 0.086, & k_{16} = 0.0011. \end{array}$$

- Others are estimated with confidence:

$$\begin{array}{llll} k_2 = 1, & k_5 = 1, & k_6 = 15, & k_8 = 1, \\ k_{10} = 1, & k_{13} = 1, & k_{14} = 0.5. & \end{array}$$

Three further Linear Conservation Constraints may be derived, introducing three further constant parameters.

$$x_5 + x_8 + x_9 + x_{10} + x_{11} = k_{17}$$

$$x_4 + x_6 + x_7 = k_{18}$$

$$x_1 + x_2 + x_3 + x_6 + x_7 + x_8 + x_9 + x_{10} + x_{11} = k_{19}$$

We work with some realistic values for these new parameters:

$$k_{17} = 100, \quad k_{18} = 50, \quad k_{19} \in \{200, 500\}.$$

However, the confidence in these estimates is not as high as the others. Ideally we would treat all three of these as symbolic parameters.

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- Converting to rationals and multiplying up to integers.
- Appending positivity constraints on all variables and free parameters.

$$0 = -200x_1x_4 - 11x_1x_5 + 860x_{11} + 10000x_6,$$

$$0 = -16x_2x_4 - 10x_2x_5 + 500x_{10} + 5x_6 + 500x_7 + 500x_9,$$

$$0 = -9x_3x_5 + 3000x_7 + 200x_8,$$

$$0 = -10x_1x_4 - 16x_2x_4 + 505x_6 + 8000x_7,$$

$$0 = -11x_1x_5 - 200x_2x_5 - 450x_3x_5 + 10000x_{10} + 860x_{11} + 10000x_8 + 10000x_9,$$

$$0 = 2x_1x_4 - 101x_6,$$

$$0 = 4x_2x_4 - 2000x_7,$$

14 polynomial equations

$$0 = 45x_3x_5 - 1092x_8,$$

11 variables

$$0 = 5x_2x_5 + 46x_8 - 500x_9,$$

1 – 3 parameters

$$0 = x_2x_5 - 150x_{10},$$

12 – 14 positivity conditions

$$0 = 11x_1x_5 + 5000x_{10} - 860x_{11},$$

denote (conjunction of) this as φ

$$0 = -k_{17} + x_{10} + x_{11} + x_5 + x_8 + x_9,$$

$$0 = -k_{18} + x_4 + x_6 + x_7,$$

$$0 = -k_{19} + x_1 + x_{10} + x_{11} + x_2 + x_3 + x_6 + x_7 + x_8 + x_9,$$

$$0 < x_1, \dots, 0 < x_{11}, 0 < k_{17}, 0 < k_{18}, 0 < k_{19}.$$

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- **Lazy Real Triangularize** (LRT). Recent work by Chen *et al.* [CDM⁺11, CM16]. Implemented in the REGULARCHAINS Library for MAPLE.

A CAD is:

- a **decomposition** meaning a partition of \mathbf{R}^n into connected subsets called **cells**;
- **(semi)-algebraic** meaning that each cell can be defined by a sequence of polynomial equations and inequalities.
- **cylindrical** meaning the cells are arranged in a useful manner - their projections (relative to a given variable ordering) are either equal or disjoint.

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Approach 1: CAD + VS in Redlog

Consider $\varphi_{k_{19}}$ as the system with all parameters except k_{19} set.

- We solve for $i \in \{1, \dots, 11\}$ eleven QE problems using VS:

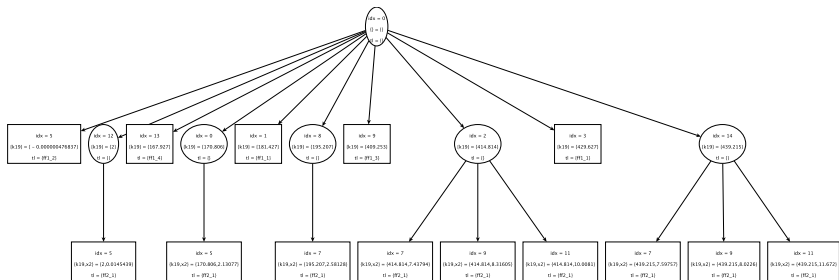
$$\varphi_{k_{19}}^{(i)} = \text{VS}(\exists x_1 \dots \exists x_{i-1} \exists x_{i+1} \dots \exists x_{11} \varphi_{k_{19}}).$$

Each $\varphi_{k_{19}}^{(i)}$ is a bivariate quantifier-free formula in k_{19} and the corresponding x_i .

- We then construct eleven 2-dimensional CADs, one for each $\varphi_{k_{19}}^{(i)}$ (projecting x_i and decomposing k_{19} axis).

Feasible in Redlog **providing** we do not extend over 0-dim k_{19} -cells. Hence accept finitely many known blind spots (a single value, hence biologically infeasible) in parameter space.

Pruned CAD tree for $\varphi_{k_{19}}^{(2)}$



- First layer decomposes k_{19} -axis.
- Rectangular cells are sections - those in top layer are the blind spots in k_{19} .
- Ovals are sectors - full dimensional cells. Over these we extend to a cylinders in the (x_2, k_{19}) -plane.
- We see that the decomposition of that cylinder either has one or three sections depending on k_{19} value.

Conclusions from Approach 1

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- ② There is a break point around $k_{19} = 409.253$ where the system changes its qualitative behaviour:
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- ❸ We may give the break point exactly as an algebraic number with degree 10 defining polynomial.

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Consider the generic equation of degree two.

```
> R := PolynomialRing([x, c, b, a]); sys := [ax^2 + bx + c = 0]
```

$R := \text{polynomial_ring}$
 $sys := [ax^2 + bx + c = 0]$

Compute a triangular decomposition of the 4-variable hypersurface it defines.

```
> dec := RealTriangularize(sys, R) : Display(dec, R);
```

$$\left[\left\{ \begin{array}{l} ax^2 + bx + c = 0 \\ -4ac + b^2 > 0 \text{ and } a \neq 0 \end{array} \right\}, \left\{ \begin{array}{l} 2ax + b = 0 \\ 4ac - b^2 = 0 \\ a \neq 0 \end{array} \right\}, \left\{ \begin{array}{l} bx + c = 0 \\ a = 0 \\ b \neq 0 \end{array} \right\}, \left\{ \begin{array}{l} c = 0 \\ b = 0 \\ a = 0 \end{array} \right\} \right]$$

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```
> LazyRealTriangularize(sys, R, output = piecewise)
```

$$\left[\begin{array}{l} [[ax^2 + bx + c = 0]] \\ \%LazyRealTriangularize([a = 0, ax^2 + bx + c = 0], polynomial_ring) \\ \%LazyRealTriangularize([-4ac + b^2 = 0, ax^2 + bx + c = 0], polynomial_ring) \\ [] \end{array} \right] \quad \begin{array}{l} 0 < -4ca + b^2 \text{ And } a \neq 0 \\ a = 0 \\ -4ac + b^2 = 0 \\ otherwise \end{array}$$

With one free parameter we can easily build an LRT for the system:

The evaluated solution component is not only triangular but:

- 1 With all but one equation linear in its main variable;
- 2 The remaining equation bivariate (one variable and the parameter);
- 3 Only two positivity constraints still explicitly stated (on the two variables in that bivariate equation).

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The unevaluated components from LRT concern only a handful of isolated positive real points - so as with Approach 1 we have a few known blind spots.

Solution Formulae

With $k_{17} = 100$ and $k_{18} = 50$ the following are valid formulae for positive real solutions at all but 3 isolated points:

$$\begin{aligned}x_{11} = & -\frac{1}{60}x_2^2 + \frac{1}{600}(10k_{19} - 10x_1 - 37x_3 + 10x_4 - 2100)x_2 \\ & - \frac{9}{200}x_3^2 + \frac{1}{600}(-27x_1 + 27x_4 + 27k_{19} - 4650)x_3 \\ & - x_1 + x_4 + k_{19} - 50,\end{aligned}$$

$$x_{10} = \frac{1}{150}x_2(x_2 + x_3 - x_4 - k_{19} + x_1 + 150),$$

$$x_9 = \frac{1}{18200}(69x_3 + 182x_2)(x_2 + x_3 - x_4 - k_{19} + x_1 + 150),$$

$$x_8 = \frac{15}{364}(x_2 + x_3 - x_4 - k_{19} + x_1 + 150)x_3,$$

\vdots

$$x_2 = \text{rational function in } x_1 \text{ and } k_{19},$$

where x_1 and k_{19} are the real positive solutions of a degree 6 bivariate polynomial equation.

To finish the Approach 2 solution we can produce a full CAD sign-invariant for that bivariate polynomial. A CAD of the (x_1, k_{19}) -plane into 135 cells takes a few seconds.

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This time we may conclude exactly 3 (instead of at least) which indicates a possible bistability region, of interest to biologists. We also have the exact solution formulae for the region.

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- Allowing k_{17} to be free and fixing $k_{19} = 500$ we find the number of positive real solutions moving from 1 to 3 to 1 breaking at $k_{17} = 85.988$ and $k_{17} = 110.869$.

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- Allowing k_{17} to be free and fixing $k_{19} = 500$ we find the number of positive real solutions moving from 1 to 3 to 1 breaking at $k_{17} = 85.988$ and $k_{17} = 110.869$.
- Similarly, allowing k_{18} to be free and fixing $k_{19} = 200$ we find there is only ever one positive real solution; but fixing $k_{19} = 500$ instead we find 3 real solutions between $k_{18} = 44.434$ and 58.329 and 1 otherwise.

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1. **Numeric:** Using the homotopy solver `BERTINI` [BHSW13].

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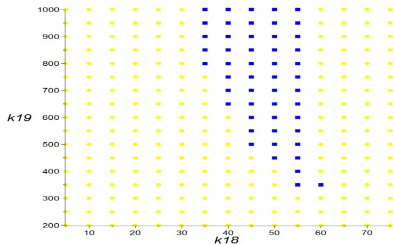
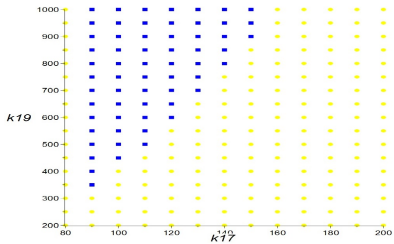
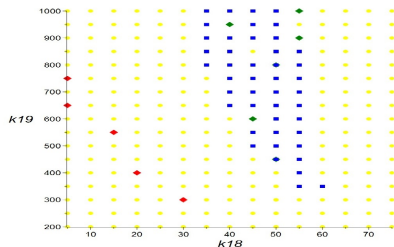
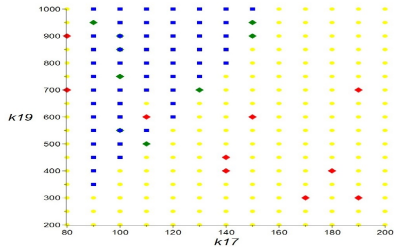
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2. **Symbolic:** Iteratively applying RT + CAD with no free parameters.

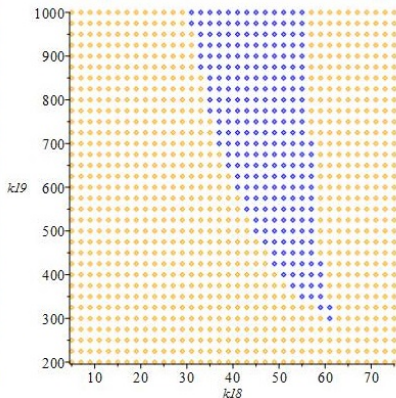
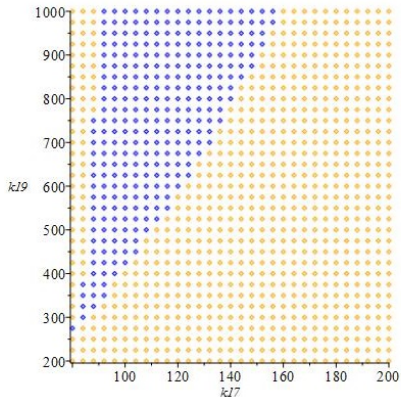
Not only did this approach avoid such errors, it even produced the images quicker than `BERTINI` for model 26 (although the timings were reversed for Model 28). Details are in [EEG⁺17].

Grid Sampling Comparison



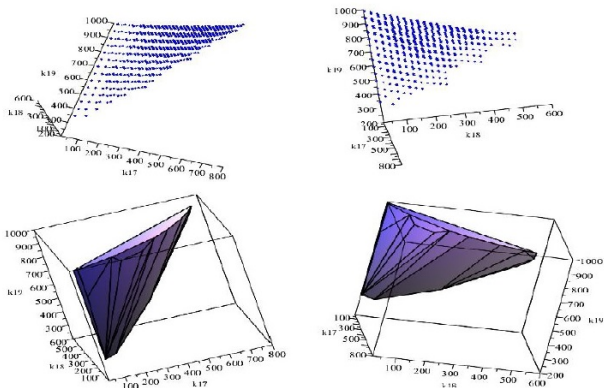
Going Further

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Convex Hull of the bistable points

- We can increase sampling density to get a better understanding of the multi-stationarity region;
- and make a 3d grid-sampling.
- But ideally we want semi-algebraic descriptions. We have results [BDE⁺19] for two free parameters:
 - Preprocessing with a graph theoretic reduction method;
 - Lazy Real Triangularize;
 - and the restricted CAD lifting of Approach 1.

Note: The blind spots are now blind line segments here.

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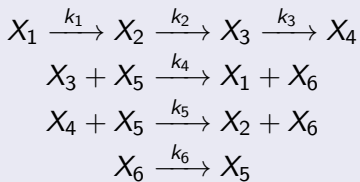
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- Problems like MAPK were, until recently, out of the scope of symbolic methods. But by combining the latest approaches progress is possible.
- The two parameter case seems in reach: see [BDE⁺19]. Three parameters?
- In either case, incorporating symbolic techniques leads to much better grid sampling.

Setting for [FS20]: Hybrid Histidine-Kinase Network (HK)



$$\left\{ \begin{array}{l} k_4 x_3 x_5 - k_1 x_1 = 0 \\ k_5 x_4 x_5 + k_1 x_1 - k_2 x_2 = 0 \\ -k_4 x_3 x_5 + k_2 x_2 - k_3 x_3 = 0 \\ -k_4 x_3 x_5 - k_5 x_4 x_5 + k_6 x_6 = 0 \\ x_1 + x_2 + x_3 + x_4 - T_1 = 0 \\ x_5 + x_6 - T_2 = 0 \end{array} \right.$$

- Variables x_i s (concentrations of species).
- Parameters k_i s (reaction rate constants) and T_i 's (constants of conservation laws).

The network is called **multistationary** if there exists a choice of parameters for which the new system of equations has more than one positive solution.

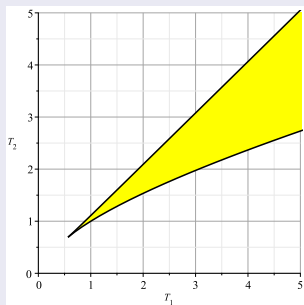
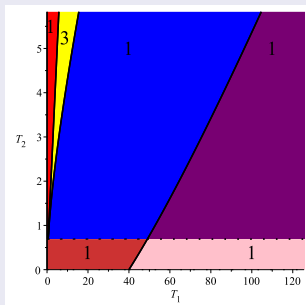
Region of multistationarity

For illustration purposes fix the following values for all parameters other than T_1 and T_2 .

$$(k_1, \dots, k_6) = (0.7329, 100, 73.29, 50, 100, 5).$$

Question

Find the region in (T_1, T_2) -space intersected with the box $[0, 5] \times [0, 5]$ where the network is multistationary.



CAD gives 6 open cells where number of steady states is invariant in each.

Number of cells grows fast, specially doubly exponential on
 $d = \text{number of variables} + \text{number of parameters}$.
Therefore only applicable on very small systems.

What is Kac-Rice formula? [Kac43]

Let $f : \mathbb{R}^N \rightarrow \mathbb{R}^N$ be a polynomial system with coefficients being polynomials on random parameters with uniform or normal distribution. Then under some conditions we can find the expected number of **positive** real roots:

$$\mathbb{E}\left(\#(f^{-1}(0) \cap \mathbf{R}_{>0}^N)\right) = \int_{\mathbf{R}_{>0}^N} \mathbb{E}(|\det(J_t f)| \mid f(t) = 0) p_t(0) dt.$$

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The key to compute Kac-Rice integral in reaction network settings

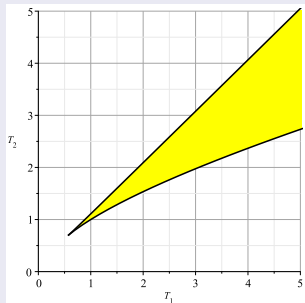
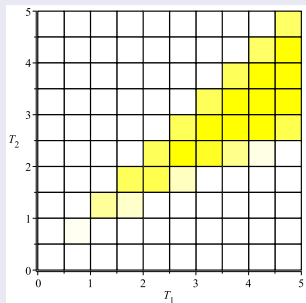
For each polynomial isolate one parameters in a linear form. The easiest choice;

- For conservation laws isolate its conserved amount T_i .
- For steady state polynomials, choose a reaction rate constant k_i . By linear operations remove its corresponding term in the rest of steady state polynomials. Then isolate it in the only steady state polynomial containing it.

Make a grid and for each sub-box compute the Kac-Rice integral with

$$T_1 \sim U([a_i, a_{i+1}]), T_2 \sim U([b_j, b_{j+1}])$$

Using Kac-Rice formula



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- 4 The computational mathematicians are seeing slightly more acceptance by the biologists — coauthors of [BDE⁺17, BDE⁺19, EEG⁺17].



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