#### Classifications Vectors

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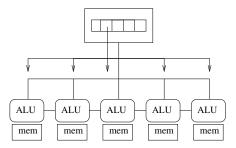
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Sometimes called a broadcast

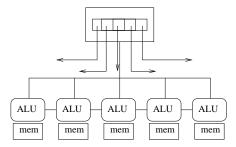
Vectors



One read goes to all cores

#### Classifications Vectors

However, as is often the case, it can be that each core wants a value from a different part of global memory. E.g., core k wants the kth element from a array



Reading a vector of values

#### Classifications Vectors

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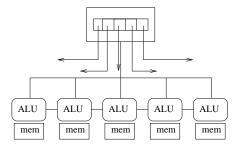
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The next 16 values are sent in the next transfer; and so on

Vectors



A single fat read goes to multiple cores

#### Classifications Vectors

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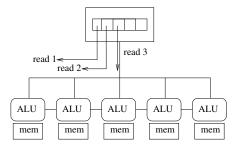
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E.g., proc k wants value  $k^2$  from the array

Vectors



Awkward distribution done in multiple reads

Vectors

Similarly for writes: e.g., core *k* writing a value to the *k*th slot in an array could be coalesced

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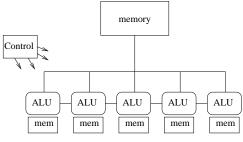
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**Exercise** Consider the case of indirecting through a pointer to global memory (a) when each core points to the same location and (b) when each core points to a different location in the global memory

**Exercise** Consider the case of indirecting through a pointer to local memory (a) when it's pointing to the same location on all cores and (b) when it's pointing to a different location on each core

Vectors

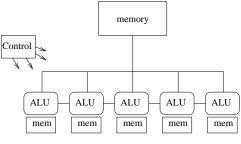
Often there is fast direct communications between neighbouring CPUs



Neighbour connections

Vectors

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Neighbour connections

This allows data to shuffle up and down the vector very quickly: many problems (e.g., differential equations solving) work on data and neighbour data in this way



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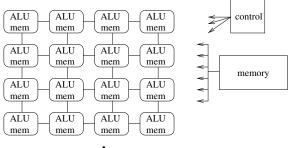
Vector processors appeared early in parallel computing as they are relatively easy to build: ALUs are relatively easy to build and replicate, while control units are complex and hard



An extension of the idea was the array processor



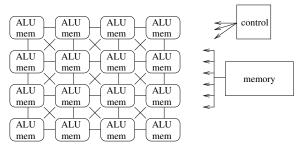
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Array processor



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Array with diagonal connections



The CPUs are in SIMD lockstep as before, but now in an array



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Fast connections in two or more directions



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More expensive than vector processors and much less common

#### Classifications Arrays

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		CPU	#CPUs	mem/CPU
DAP	1979	1 bit	4k	4k bits
CM	1983	1 bit	64k	few kB
MPP	1983	1 bit	16k	1 kB
MasPar	1990	4 bit	16k	16kB
MasParll	1992	32 bit	64k	64kB

DAP: ICL Distributed Array Processor CM: Connection Machine (pretty lights) MPP: Goodyear Massively Parallel Processor



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Vector/array processing processors are important due to their influence on the design of GPUs



# Shared, distributed and vector processors are the three major architectures used today



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But others have been tried, with varying levels of success

Pipelines, Systolic Arrays

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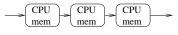


Process pipeline

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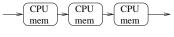
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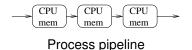
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**Exercise** Could this be classified MISD?

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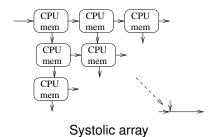
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Part of the reason why digital TV is delayed relative to realtime is that the encoding of the picture goes through a big pipeline before it is transmitted: there is an inherent *latency* in pipelines

Pipelines, Systolic Arrays

Systolic arrays are the obvious extension



but it is unclear if these were ever built

Extensions of von Neumann

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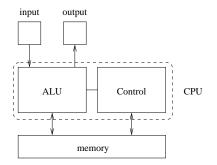
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Is there a model that encapsulates multiprocessors in the same way?

There are many contenders, but no obvious winner

Extensions of von Neumann

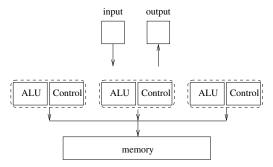
#### We have the original von Neumann 5 box model



von Neumann 5 box model

Extensions of von Neumann

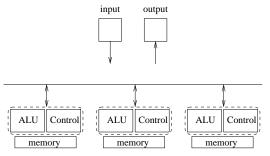
### Shared memory MIMD



Shared memory box model

Extensions of von Neumann

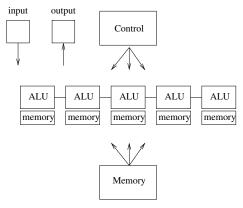
### Distributed memory MIMD



Distributed memory box model

#### Extensions of von Neumann

#### Vector processor



Vector processor memory box model

Extensions of von Neumann

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Extensions of von Neumann

Perhaps there just isn't a single extension of von Neumann that is suitable as a one-size-fits-all solution

Or perhaps we just haven't thought of it yet?

Extensions of von Neumann

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As with von Neumann, the idea is that you

- write your program in accordance with the model
- the model maps well onto all kinds of real hardware
- therefore your program maps well onto all kinds of real hardware

Extensions of von Neumann

Firstly: PRAM

Extensions of von Neumann

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- Concurrent Read Exclusive Write (CREW). Each memory location can be read by many processors simultaneously, but written by just *one* processor at a time (c.f. global memory in a vector processor)

Extensions of von Neumann

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- Memory is unlimited. This assumption is also often made in analysis of uniprocessor algorithms

Extensions of von Neumann

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And people want to run programs on datasets of ever-increasing size

Extensions of von Neumann

So you analyse your program, counting numbers of memory accesses it makes (according to which of EREW/CREW/CRCW you have chosen) and this gives you a measure of the time your program will take to run



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But it gives you a rough idea and it is extensively used in analysis of parallel algorithms: we'll have some examples later

Extensions of von Neumann

Next: **BSP** 

Extensions of von Neumann

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The Bulk Synchronous Parallel model

Extensions of von Neumann

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The Bulk Synchronous Parallel model

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Good for distributed, but can be used for shared memory where you just have smaller communication costs

Extensions of von Neumann

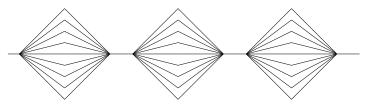
A computation is modelled as a sequence of *supersteps* 

Extensions of von Neumann

A computation is modelled as a sequence of *supersteps* 

- each processor does some computation (MIMD, but could be SIMD)
- each processor does some communication
- each processor waits at a global *barrier* until everybody has finished their communications. This is the "bulk synchronous" part
- repeat

Extensions of von Neumann



**BSP** supersteps

Extensions of von Neumann

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But those analyses tend to be a better match to realistic hardware

Extensions of von Neumann

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This might be the source of the confusion in parallel hardware, but we have to live with it

So we need to look at how to analyse parallel algorithms

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They are quite crude, but effective

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Ideally we'd like  $S_p = p$ , but this never happens



#### Usually $S_p$ is much smaller than p for several reasons



# Usually $S_p$ is much smaller than p for several reasons Firstly, there is communications overheads between processors



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Time spent communicating is time not spent computing





For example, speedups on distributed memory machines can be reduced as the cost of communications is quite high



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But speedups can improve for a larger computation where the *relative* cost of communications drops



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Remember clusters are used for large problems where the emphasis is on size, not speed



In really bad cases,  $S_p < 1$ , i.e., our parallel program goes *slower* than our sequential program even though we've thrown all this expensive hardware at it!



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This is more common than we'd like