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There is now another, different, problem with this code!

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We can't rely (in a MIMD architecture) on the two loops on different cores running at the same time and finishing at the same time

Timings in the system may have the two loops running in any conceivable arrangement of before, after or overlapped

Synchronisation

```
1 2
for (i = 0; i < 50; i++) {
    if (val[i] > 0)
        count1 = count1 + 1;
} for (j = 50; j < 100; j++) {
    count = count1 + count2;
        if (val[j] > 0)
            count2 = count2 + 1;
}
```

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Another sequentialisation!

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Finally 1 awakes and gets the wrong count2

This does happen and is a source of bugs

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Note that even though both locks and semaphores are flags, they are very different things! Beware it is common for people to confuse the two

Semaphores are manipulated by two atomic operations P and V that symbolically act atomically as:

On finding s = 0 a thread will suspend itself; when awoken it will re-attempt to set the semaphore: and it will often succeed, unless a third thread comes along and gets the semaphore first

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Other names for V are: signal, down, unlock, exit, close

P stands for "proberen", V for "verhogen", which are Dutch for "test" and "increase"

Semaphores

Semaphores synchronise across threads:

do something
wait(s)
read data

prepare data
signal(s)
carry on

Thread 1 waits until thread 2 has prepared some data before reading it

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The signal and wait might happen in any order

#### Concurrency Primitives Counting Semaphores

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When initialised with the value *n*, this will allow *n* threads to open the semaphore before blocking

**Counting Semaphores** 

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Or 4 if they are philosophers...

Mutual exclusion with semaphores happens to be easy:

wait(s);
<CR>
signal(s);

Wait for the semaphore; signal it's free when you are done

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```
wait(s);
<CR>
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```

Wait for the semaphore; signal it's free when you are done

But don't do this: it's better to use locks here. Semaphores are more general than locks: they allow a thread to suspend itself and be awoken by another thread when some condition is true

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Semaphores should be used across threads, mutexes must not

The locking effect is in some sense incidental: more useful is using semaphores to synchronise

POSIX semaphores:

```
#include <semaphore.h>
sem_t sem;
int sem_init(sem_t *sem, int pshared, unsigned int value);
int sem_destroy(sem_t *sem);
int sem_wait(sem_t *sem);
int sem_post(sem_t *sem);
int sem_trywait(sem_t *sem);
```

"post" for signal

**Exercise** Add a semaphore to the count1/count2 example to get thread 1 to wait for thread 2 before doing the final sum

**Exercise** Then add another semaphore to get thread 2 to wait for thread 1 before starting

Another synchronisation primitive is *barriers* (occasionally called *rendezvous*)

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This allows us to synchronise parts of the program: recall supersteps

Suppose we have a list of numbers we want to square then add in pairs

```
for (i = 0; i < 100; i++) {
    v[i] = v[i]*v[i];
}
for (i = 0; i < 100; i++) {
    s[i] = v[i] + v[99-i];
}</pre>
```

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}</pre>
```

We can parallelise this by having (say) 4 threads; each thread squares a block of values; then they add a block of values

1	2	3	4
v[0]^2	v[25]^2	v[50]^2	v[75]^2
v[1]^2	v[26]^2	v[51]^2	v[76]^2
v[2]^2	v[27]^2	v[52]^2	v[77]^2
	• • •	• • •	
v[24]^2	v[49]^2	v[74]^2	v[99]^2
v[0]+v[99]	v[25]+v[74]	v[50]+v[49]	v[75]+v[24]
v[1]+v[98]	v[26]+v[73]	v[51]+v[48]	v[76]+v[25]
 v[24]+v[75]	 v[49]+v[50]	··· v[74]+v[25]	 v[99]+v[0]
v[1]+v[98]	v[26]+v[73]	v[51]+v[48]	v [76] +v [25]

Again, the above might work sometimes, or many times, but it is buggy

The problem here is again that the threads may not all be running at the same speed: perhaps one thread is interrupted and descheduled by the OS; or memory access is not uniform speed; or many other factors

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			v[76]^2
v[24]^2	v[49]^2	v[74]^2	v[97]^2
v[0]+ <b>v[99]</b>	v[25]+v[74]	v [50] +v [49]	v[98]^2
v[1]+v[98]	v[26]+v[73]	v[51]+v[48]	v[99]^2
			v[75]+v[24]
v[24]+v[75]	v[49]+v[50]	v[74]+v[25]	v[97]+v[2]
			v[98]+v[1]
			v[99]+v[0]

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v[24]+v[75]	v[49]+v[50]	v[74]+v[25]	v[97]+v[2]
			v[98]+v[1]
			v[99]+v[0]

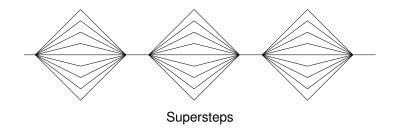
This is how we get the wrong answer: again just because the lines of code for the adds follows the lines of code for the squares make us believe every add happens after every square

We need to synchronise all the threads at the end of the squares before allowing them to continue with the adds

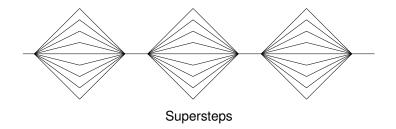
b = make\_barrier(4); <parallel squares> <parallel squares> <parallel squares> ... barrier\_wait(b); barrier\_wait(b); barrier\_wait(b); ... <parallel adds> <parallel adds> ...

Only when all 4 threads have reached the barrier can they all proceed

Barriers are good for the superstep style of programming

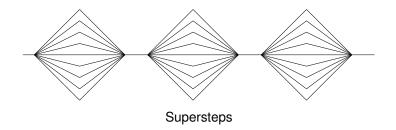


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Thus barriers are best when all the threads are doing roughly the same amount of work

```
#include <pthread.h>
pthread_barrier_t barrier;
int pthread_barrier_init(
    pthread_barrier_t *restrict barrier,
    const pthread_barrierattr_t *restrict attr,
    unsigned count);
int pthread_barrier_destroy(pthread_barrier_t *barrier);
int pthread_barrier_wait(pthread_barrier_t *barrier);
```

A barrier can be reused immediately after it has released its threads; it has a fixed value of *n* set when it is initialised

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A barrier can be reused immediately after it has released its threads; it has a fixed value of *n* set when it is initialised

**Exercise** Have a look at the return value from pthread\_barrier\_wait

**Exercise** Fix the count1/count2 problem with barriers

**Exercise** Both semaphores and barriers are about synchronisation. Think about how you might implement barriers using semaphores

**Exercise** Think about how you might implement semaphores using barriers

**Condition Variables** 

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Condition variables are normally associated with a mutex, and are used *inside* a critical region protected by that mutex

#### **Condition Variables**

```
1
get_lock(mx);
<CR>
condvar_wait(cv, mx);
(wait)
<CR>
free_lock(mx);
```

2
get\_lock(mx);
<CR>
condvar\_signal(cv);
free\_lock(mx);

 ${\tt condvar\_wait}$  releases the mutex and waits on the condition variable

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```
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 ${\tt condvar\_wait}$  releases the mutex and waits on the condition variable

When the other thread signal signals and releases the mutex, the first thread regains the mutex and continues within the critical region

**Condition Variables** 

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With a broadcast all other threads are marked as ready to run, but only one will regain the lock; the others will blocked on the lock as normal

One will get the lock when the first thread releases it; and so on

**POSIX Condition Variables** 

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The pthread\_cond\_signal() function shall unblock at least one of the threads that are blocked on the specified condition variable cond

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The specification for pthread\_cond\_signal says

The pthread\_cond\_signal() function shall unblock at least one of the threads that are blocked on the specified condition variable cond

"at *least* one": there is a (rare) problem of *spurious wakeups* that is in general too expensive to avoid

This just means you have to be a bit formulaic about the use of condition variables and always have a *condition* to test before continuing

#### 

Thread 1 might get awoken spuriously but it doesn't want to continue until the next iteration

**POSIX Condition Variables** 

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Condition variables are very useful, but a bit of a pain to use

**Concurrency Primitives** 

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All eventually go back to the underlying hardware or software support

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"Primitive" is actually a good description as they are all very low level

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- (b) the time spent in executing the code of the primitive

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- (a) the time spent blocked as a necessary part of its function, e.g., wait on a lock
- (b) the time spent in executing the code of the primitive

Note part (a) isn't really a limitation of the primitive: it's necessary if it is to work at all. It is (b) that the implementation of a primitive seeks to minimise

Higher Level

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These come in many forms

**Higher Level** 

Concurrency control can be supported in a high-level language as

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 added in to an existing language, in library support. We have seen some of this already: the POSIX examples

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We shall be looking at all of these approaches

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The hope (and economics) is we can take existing code using an existing language and modify it

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The easiest way is to leave the language itself untouched, just adding a library of functions that do parallelism

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But you can't just add a parallel library to a sequential language and hope everything is OK

Threads again

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And some hardware optimisations can break parallel code

**Compiler Reordering** 

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For example, main memory access is (relatively) slow, so if the value of a variable is needed, the compiler might try to start loading it earlier than the code might suggest

**Compiler Reordering** 

Given code

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```

The effect is the same, but it goes a little faster. The compiler in effect rewrites your code

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A compiler only seeing the code for B may conclude that the variables cont and x are independent and so (perhaps for whatever reason) it can rearrange the code as

cont = 1; x = 42;

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The problem is that there is a hidden relationship between the variables x and cont that is in the mind of the programmer, but is not expressed in the code

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Example. Consider the code:

Explain how it might print 0 twice, even though it appears we always print after an update